

Automated Transporting Solutions

C-MATIC

Capacity 0.6 t - 1.5 t | Series 8924/25/26

ION

Compact, automated solution for the efficient transport of goods over short and medium distances

- → Effortless transport on load tables capable of travelling under or between transfer stations
- \rightarrow Rotating plate to reorientate the load
- \rightarrow Models with capacities from 600 to 1500 kg
- → Intelligent software control with efficient orientation via QR codes
- → Safety technology for hazard-free operation in dedicated areas

TECHNICAL DATA (according to VDI 2198)

	1.1	Manufacturer (abbreviation)		Linde MH	Linde MH	Linde MH
Characteristics	1.2	Manufacturer's type designation		C-MATIC 06	C-MATIC 10	C-MATIC 15
	1.2a	Series		8924-02	8925-02	8926-02
	1.3	Drive		Electric	Electric	Electric
	1.4	Operation		Automated	Automated	Automated
	1.5	Rated capacity/rated load	Q (t)	0.6	1.0	1.5
Weight	2.1	Service weight	kg	145	2051)	215 ¹⁾
sis	3.1	Tyres: solid rubber, superelastic, pneumatic, polyurethane		Polyurethane	Polyurethane	Polyurethane
chas	3.4	Additional wheels (dimensions)		200 × 40	200 × 40	200 × 40
Tyres/chassis	3.5	Wheels, number front/rear (x = driven wheels)		2x +2	2x +2	2x +2
Ţ	3.6	Tread, front	b10 (mm)	668	758	758
	4.4	Lift	h3 (mm)	55	60	60
	4.15	Height, lowered	h11 (mm)	240	260	260
	4.16	Length of loading surface	13 (mm)	Ø 680	950 ²⁾	1000 ²⁾
SE	4.18	Width of loading surface	b9 (mm)	Ø 680	750 ²⁾	780 ²⁾
nsic	4.19	Overall length	l1 (mm)	956	1182	1182
Dimensions	4.21	Overall width	b1/b2 (mm)	730	832	832
٥	4.33	Load dimension b12 × I6	b12 × l6 (mm)	900 × 900 ³⁾ (780 × 780) ⁴⁾	1200 × 1200 ³⁾⁵⁾ (1080 × 1080) ⁴⁾	1200 × 1200 ³⁾⁵⁾ (1080 × 1080) ⁴⁾
	4.34	Aisle width predetermined load dimensions	Ast (mm)	14736)	18976)	18976)
	4.35	Turning radius	Wa (mm)	478	618.5 ⁷⁾	618.5 ⁷⁾
9	5.1	Travel speed, laden/unladen	km/h	5.4 / 7.2	4.3 / 5.4	4.3 / 5.4
nan	5.2	Lifting speed, laden/unladen	m/s	0.29	0.29	0.29
Performance	5.3	Lowering speed, laden/unladen	m/s	0.21	0.21	0.21
Perí	5.8	Max. gradeability, laden/unladen	%	<5% ⁸⁾	<5% ⁸⁾	<5% ⁸⁾
Electric- engine	6.4	Battery voltage/nominal capacity KS	(V)/(Ah) or kWh	48/36 ⁹⁾	48/38.5 ⁹⁾	48/38.5 ⁹⁾
	6.6	Energy consumption according to DIN EN 16796	kWh/h	0.25 ¹⁰⁾	0.310)	0.5210)
Additional data	10.7	Sound pressure level LpAZ (at the operator's seat)	dB(A)	<75	<75	<75

- 1) Adaptor plate weight for C-MATIC 10: (h13 = 450 mm, +70 kg), (500 mm, +75 kg) (700 mm, +94 kg); C-MATIC 15: (450 mm, +62 kg), (500 mm, +66 kg), (700 mm, +86 kg)
- 2) Loading platform rotation diameter: C-MATIC 10: Ø 1060 mm; C-MATIC 15: Ø 1114 mm
- 3) With loading platform: tables as load carrier are required
- 4) Load inner dimensions (l6.1 × b14)
- 5) Pallet handling with adaptor plate (I3 × b9 = 1200 × 887 mm) with 3 fixation positions I6: 1016 mm (Position 1), 1000 mm (Position 2), 800 mm (Position 3) b12: <1219 mm
- 6) Including a 200 mm (min.) operating aisle clearance. With adaptor plate and load dimensions (b12 × 16) of Euro pallet (1200 × 800) = 1642 mm; UK pallet (1200 × 1000) = 1762 mm: US pallet (1219 × 1016) = 1898 mm
- 7) Unloaded rotation diameter C-MATIC 06/10/15: Ø 956/1237/1237 mm with adaptor plate: C-MATIC 10/15: Ø 1411 mm
- 8) Suggested max. climbing angle is ≤3%, allowed step height ≤5 mm, traversable gap ≤15 mm
- 9) Li-ION battery
- 10) Battery running time (50% fully loaded) C-MATIC 06/10/15: 9 h/7.5 h/6.5 h; Battery charging time from SOC 0 \sim 100%: \sim 1.5 h

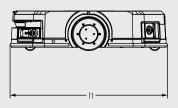
PLATFORM AND ADAPTOR PLATE

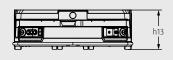
1) h13 = height from floor to top of vehicle (lift lowered)

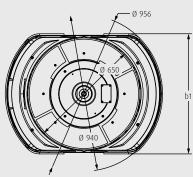
2) h2 = free lift

C-MATIC 06	Lift	Height of platform extended max.	Pick up and drop-off height	Max. height of CoG (from floor)	Max. displ. of CoG		Max. capacity	Load carrier type	
h13 ¹⁾ (mm)	h3 (mm)	h4 (mm)	h13 ¹⁾ + h2 ²⁾ (mm)	hc1 (mm)	c1 (mm) c2 (mm)		Q (kg)	l6 × b12 [× m2] (mm)	
240	55	295	270	740	110	140	600	Table 900 × 900 × 270	
C-MATIC 10	Lift	Height of platform extended max.	Pick up and drop-off height	Max. height of CoG (from floor)	Max. displ. of CoG		Max. capacity	Load carrier type	
h13 ¹⁾ (mm)	h3 (mm)	h4 (mm)	h131) + h22) (mm)	hc1 (mm)	c1 (mm)	c2 (mm)	Q (kg)	l6 × b12 [× m2] (mm)	
260	60	320	290	890	120	160	1000	Table 1200 × 1200 × 290	
290	60	350	320	1000	140	166	1000	Pallets I6 × b12	
450	60	510	480	840	127	153	1000	Pallets I6 × b12	
500	60	560	530	790	125	151	900	Pallets I6 × b12	
700	60	760	730	590	117	143	900	Pallets 16 × b12	
C-MATIC 15	Lift	Height of platform extended max.	Pick up and drop-off height	Max. height of CoG (from floor)	Max. displ. of CoG		Max. capacity	Load carrier type	
h13 ¹⁾ (mm)	h3 (mm)	h4 (mm)	h13 ¹⁾ + h2 ²⁾ (mm)	hc1 (mm)	c1 (mm)	c2 (mm)	Q (kg)	l6 × b12 [× m2] (mm)	
260	60	320	290	890	120	160	1500	Table 1200 × 1200 × 290	
290	60	350	320	1000	140	166	1500	Pallets I6 × b12	
450	60	510	480	840	127	153	1500	Pallets I6 × b12	
500	60	560	530	790	125	151	1300	Pallets I6 × b12	
700	60	760	730	590	117 143		1300	Pallets I6 × b12	

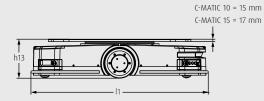
C-MATIC 06



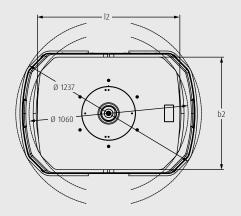




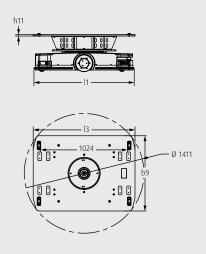
C-MATIC 10, C-MATIC 15

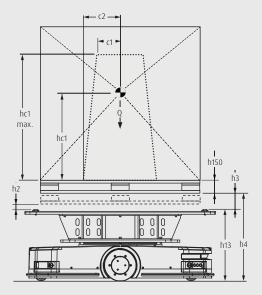






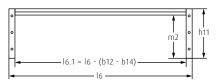
ADAPTOR PLATE: C-MATIC 10, C-MATIC 15



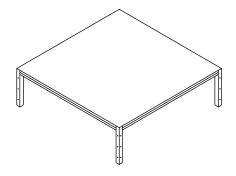


APPLICATION INFORMATION

PLATFORM: TABLE REQUIREMENTS





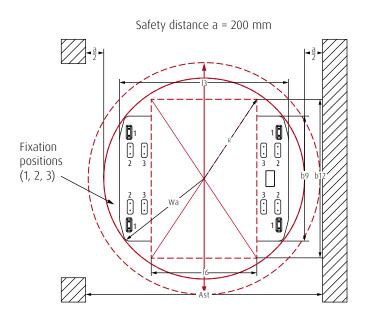




A QR code must be located centrally underneath the table for load identification and orientation.

Manufacturer's type designation	C-MATIC 06	C-MATIC 10	C-MATIC 15	
Dimension I6 × b12 × m2 (mm)	900 × 900 × 270	1200 × 1200 × 290	1200 × 1200 × 290	
Inner Dimensions I6.1 × b14(mm)	780 × 780	1080 × 1080	1080 × 1080	
Capacity (kg)	600	1000	1500	

ADAPTOR PLATE: PALLET REQUIREMENTS



Ast =
$$2 \times max$$
 (Wa, R) + a, with a = 200 mm

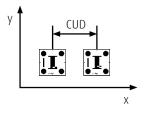
$$R = \sqrt{\left(\frac{b12}{2}\right)^2 + \left(\frac{16}{2}\right)^2}$$

Adaptor plate	C-MATIC 10	C-MATIC 15	Ast (mm)
Adaptor plate dimensions I3 × b9 (mm)	1200 × 887	1200 × 887	1611 mm
Load dimensions (16 × b12)	Fixation position 1, 2 or 3		
EPAL1, CP2: 800 × 1200 mm	Position 3	Position 3	1642 mm
EPAL3, CP1: 1000 × 1200 mm	Position 2	Position 2	1762 mm
Australia, GMA and North America: 1016 × 1219 mm	Position 1	Position 1	1898 mm

LOCALISATION TECHNOLOGY

The max. QR codes unit distances (CUD) is limited to 1500 mm for vehicle localization.

The different models are optimized for a standard CUD for loads without overhang.



Manufacturer's type designation	Standard CUD (mm × mm)
C-MATIC 06	1000 × 1000
C-MATIC 10	1350 × 1350
C-MATIC 15	1350 × 1350

STANDARD AND OPTIONAL EQUIPMENT

	Manufacturer's type designation/equipment	C-MATIC 06	C-MATIC 10	C-MATIC 15
Off board software	Smart routing algorithm	0	0	0
	Smart charging logic	0	0	0
	Interfaces to existing WMS, ERP, etc	0	0	0
	Interfaces with infrastructure: doors, conveyors, etc	0	0	0
	Interfaces with Linde Warehouse Management Systems	0	0	0
ard	QR code navigation	•	•	•
On board software	QR code load identification	•		•
On sof	User-friendly log-on to the vehicle	•	•	•
	Personal detection safety scanner in main direction of travel	•	•	•
Safety	Safety field switches between lifted and lowered platform	•	•	•
Saf	Emergency stop buttons on all sides (left and right corners at both front and rear)	•	•	•
	Safety bumper around the vehicle (front, side, rear)	•	•	•
	Positional accuracy ±10 mm	•	•	•
tion	Stop accuracy ±5 mm	•	•	•
igat	Angular accuracy ±1°	•	•	•
Navigation	Navigation QR codes with interval 1000 × 1000 mm	0	_	_
	Navigation QR codes with interval 1350 × 1350 mm	_	0	0
HMI interface	Control buttons	•	•	•
HMI erfa	LED indicators	•	•	•
<u>i</u> =_	Depending on situation plays warning sounds and/or voice package	•	•	•
	QR code load table identification			
	Turn, transport and drop load through 90°, 180° and 270°	•		•
	Load table dimensions 900 × 900 mm			
Operation/ load handling	Load table dimensions 1200 × 1200 mm	_		0
atio	Adaptor plate for pick and drop station at height = 320 mm			
per d h	Adaptor plate for workstations at height = 480 mm	_		0
0	Adaptor plate for conveyor at height = 530 mm			
	Adaptor plate for heights between h13 = 290 mm and 700 mm	_		
	Differential drive with dual wheels	•	•	•
	Turn on the spot with and without locked platform	•	•	•
nment	Wifi communication	•	•	•
Energy Environment	Ambient operating temperature +0 - +40°C	•	•	•
rgy	Li-ION battery	•	•	•
Ene	Automatic Opportunity Charging Connector	•	•	•
-	Switch for automated or maintenance mode	•	•	•
vice	Plug for Hand Control Unit	•	•	•
Service	Hand Control Unit	0	0	0
	Ramp to operate C-MATIC from delivery pallet	0	0	0

• Standard equipment

Optional equipment

– Not available

■ Special Equipment

CHARACTERISTICS



Dynamic safety fields

Safety

- → Laser scanner for reliable detection of vehicle's surroundings
- → Immediate reaction to people, other vehicles or obstacles
- → Ideal combination of maximum productivity and highest possible safety
- → Stable collision protection and emergency stop switch for additional protection



Handling

- → Orientation based on QR codes on the floor
- → Calculation of the optimal route for each individual transport job
- → QR codes on optional transport tables for load tracking
- → Direct transport of pallets with adaptor plate for different transfer heights
- → Optional self-charging station for fully automated battery charging



Flexible load handling

Service

- → Robust technology and long maintenance intervals for maximum availability
- → Easy access to all main components for fast maintenance
- → Rapid fault diagnosis via cable connection

Low-maintenance design



Customer process focus as a standard

Sales and realisation

- → Project-specific concept design including dynamic simulation and proof of concept on site if required
- → Combination of manual handling processes and the degree of automation can be optimised to fit the customer needs
- → One face to the customer for the whole process from first contact to the lifecycle phase
- → Intelligent, scalable software solutions to provide customers with full control of their processes
- → Project management and commissioning according to Linde standards with unified tools and templates over the entire network

Presented by:

Subject to modification in the interest of progress. Illustrations and technical specifications could include options and are not binding for actual constructions. All dimensions subject to usual tolerances.



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Printed in Germany | DS_C-MATIC_8924-02_8925-02_8926-02_en_C_0424